# **Reduction Revisited:** Verifying Round-Based Distributed Algorithms

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**INRIA Nancy & LORIA** 







joint work with Bernadette Charron-Bost, LIX & CNRS

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Reduction Revisited

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```
integer turn = 0;
                      boolean req0, req1 = false;
process P0
                                                process P1
loop
                                                loop
  nc_0: skip;
                                                   nc_1: skip;
  rq_0: req0 := true;
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  ps_0: turn := 1;
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```

• Critical section can be abstracted to atomic step

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Is it okay to combine the following actions into an atomic step?
statements rq<sub>i</sub> and ps<sub>i</sub>

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- **1** statements  $rq_i$  and  $ps_i$
- 2 statements  $rq_i$ ,  $ps_i$ , and  $wt_i$

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### Outline

### 1 Reduction Theorems for the Verification of Concurrent Programs

- 2 Fault-Tolerant Distributed Computing
- 3 Reduction for Round-Based Distributed Algorithms
- Experiments: Verification of Consensus Algorithms
- 5 Conclusion

### Reduction: overall idea

- Justify combining subsequent operations into an atomic step
- Fewer atomic steps  $\rightsquigarrow$  simpler verification

#### Theorem (folklore)

One can pretend that a sequence of statements is executed atomically *if it contains at most one access to a shared variable.* 

- Folk theorem justifies combining cs<sub>i</sub> and ex<sub>i</sub> (previous example)
- Folk theorem does not justify combining rq<sub>i</sub> and ps<sub>i</sub>

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- Consider the single-process program where initially *x* = *y*

y := x + 1; x := y

Since no variable is shared, it should be equivalent to

$$\langle y := x + 1; x := y \rangle$$

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- Consider the single-process program where initially x = y

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Since no variable is shared, it should be equivalent to

 $\langle y := x + 1; x := y \rangle$ 

But the latter program satisfies  $\Box(x = y)$  !

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# Left and right movers

### Definition (Lipton 1975)

An action *a* is a right mover if whenever  $\alpha ab$  is a computation where *a* and *b* are performed by different processes then  $\alpha ba$  is also a computation and these computations result in the same state. The definition of a left mover is symmetrical.

- Right mover  $s \xrightarrow{ab} t \Rightarrow s \xrightarrow{ba} t$  for all b
  - right commutes with every action of different processes
  - example: acquisitions of resources (e.g., semaphores)
- Left mover  $s \xrightarrow{ba} t \Rightarrow s \xrightarrow{ab} t$  for all b
  - left commutes with every action of different processes
  - example: releases of resources

R.J. Lipton. Reduction: A Method of Proving Properties of Parallel Programs. CACM 18(12):717-721, 1975.

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### Left and right movers in example

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#### • Actions rq<sub>i</sub> are right movers

- ▶ in particular, cannot make **await** condition of other process true
- formally,  $s \xrightarrow{rq_0 wt_1} t$  implies  $s \xrightarrow{wt_1 rq_0} t$

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- Actions cs<sub>i</sub> and ex<sub>i</sub> are left movers

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- ▶ in particular, cannot make **await** condition of other process true
- ► formally,  $s \xrightarrow{rq_0 wt_1} t$  implies  $s \xrightarrow{wt_1 rq_0} t$
- Actions cs<sub>i</sub> and ex<sub>i</sub> are left movers
- Actions  $ps_i$  and  $wt_i$  are neither left nor right movers

## Lipton's reduction theorem

#### Theorem (Lipton 1975)

Suppose that  $A = A_1; ...; A_k$  is such that for some *i*:

- $A_1, \ldots, A_{i-1}$  are right movers,
- $A_{i+1}, \ldots, A_k$  are left movers,
- and each  $A_2, \ldots, A_k$  can always execute.

and let P/A denote the program obtained from P by replacing  $A_1; \ldots; A_k$  by  $\langle A_1; \ldots; A_k \rangle$ .

Then P halts iff P/A halts and the final states of P equal the final states of P/A.

#### Preservation of deadlock-freedom and partial correctness

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# Application to example

Lipton's theorem justifies reduction to

```
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         skip;
                                                              skip;
         req0 := false;
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endloop
                                                    endloop
```

#### ... but only for proving absence of deadlock

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# Doeppner's reduction theorem

#### Theorem

*Let*  $\Pi$  *be a program and S have the form* R*;*  $\langle A \rangle$ *;* L *where* 

- all actions in R are right movers and
- all actions in L are left movers.

Let in(S) be true iff control resides inside S and Q be an arbitrary predicate.

*Then Q is an invariant of*  $\Pi$ */S iff*  $Q \lor in(S)$  *is an invariant of*  $\Pi$ *.* 

- Generalization of Lipton's theorem to invariant reasoning
- Can be used for proving mutual exclusion of example program

T.W. Doeppner. Parallel program correctness through refinement. POPL 1977 (ACM), pp. 155-169.

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### Other reduction theorems

- R. Back: Refining atomicity in parallel algorithms (1988)
  - first reduction theorem for total correctness
  - needs commutativity hypotheses for actions outside reduced block
- L. Lamport, F. Schneider: Pretending Atomicity (1989)
  - generalization of Doeppner's theorem
  - preservation of invariants Q of II by reduction (explicit reasoning about control being external to reduced block)
- E. Cohen, L. Lamport: Reduction in TLA (1998)
  - reformulation of Lamport & Schneider in TLA
  - extension to (certain) liveness properties

### Reduction Theorems for the Verification of Concurrent Programs

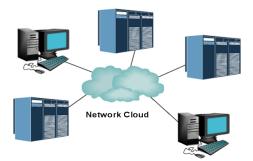
### 2 Fault-Tolerant Distributed Computing

3 Reduction for Round-Based Distributed Algorithms

#### Experiments: Verification of Consensus Algorithms

#### 5 Conclusion

# Fault-tolerant distributed algorithms



- local computation of nodes
- asynchronous communication over network
- components may fail: replication & fault-tolerance
- precisely state and prove correctness properties

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### Representative problem: consensus

- N nodes (processes) agree on a value
  - each node proposes a value initially
  - eventually nodes decide a common value
  - nodes or communication links may fail
- Formal definition: conjunction of four properties

integrity	decided value is among the initial proposals
irrevocability	decisions cannot be undone
agreement	any two nodes decide same value
termination	all (non-failed) nodes decide eventually

#### Fundamental problem in fault-tolerant distributed computing

# Why is this hard?

#### Theorem (Fischer, Lynch, Paterson 1985)

*The Consensus problem cannot be solved in an asynchronous system where at least one process may fail (by crashing).* 

• But: many consensus algorithms exist (and work well in practice)

# Why is this hard?

### Theorem (Fischer, Lynch, Paterson 1985)

*The Consensus problem cannot be solved in an asynchronous system where at least one process may fail (by crashing).* 

- But: many consensus algorithms exist (and work well in practice)
- Basis: relax some assumption of FLP theorem
  - introduce timeouts: being late is a failure
  - assume reliable (broadcast) communication
  - augment system by an oracle to detect failures
- Verification of consensus algorithms
  - difficult proofs ... often absent or informal
  - DiskPaxos: careful paper proof (30 pages for 0.5 page algorithm)

#### • Can we help make verification simpler?

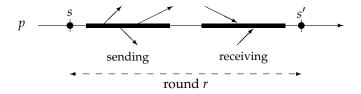
### Heard-Of Model (Charron-Bost & Schiper, 2006)

- Algorithmic model for fault-tolerant distributed algorithms
  - uniform treatment of all (benign) errors
  - do not identify "culprit" or "type" of failure

### Heard-Of Model (Charron-Bost & Schiper, 2006)

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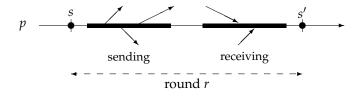
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### Heard-Of Model (Charron-Bost & Schiper, 2006)

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- rounds: local structure of process computation
- state s' computed from s and received messages
- ▶ heard-of set *HO*(*p*, *r*): processes from which messages are received
- communication-closed rounds: discard late messages

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# Formal representation of HO algorithms

- Collection of processes  $(State_p, s_{0,p}, S_p^r, T_p^r)_{p \in Proc, r \in \mathbb{N}}$ 
  - ▶ process states: sets  $State_p$  with initial states  $s_{0,p} \in State_p$
  - message sending and state transition

 $\begin{array}{l} S_p^r : State_p \times Proc \to Msg \\ T_p^r : State_p \times (Proc \rightharpoonup Msg) \to State_p \end{array}$ 

- domain of second argument of  $T_p^r$ : heard-of set HO(p, r)
- For simplicity: deterministic processes
  - algorithm behavior determined by collection of heard-of sets
  - extension to non-deterministic processes straightforward

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### Communication predicates

- Algorithms do not work in presence of arbitrary failures
  - safety: restrict number or extent of errors
  - liveness: assume eventual functioning of components

#### • Sample communication predicates

non-split rounds $\forall p, q, r : HO(p, r) \cap HO(q, r) \neq \emptyset$  $\leq f$  failures $\forall p, r : |HO(p, r)| \geq N - f$ event. uniform $\exists r_0 \in \mathbb{N}, P \subseteq Proc : \forall r \geq r_0, q \in Proc : HO(q, r) = P$ 

#### • Observations (Charron-Bost & Schiper)

▶ standard failure assumptions can be expressed in terms of HO sets

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# HO Consensus Algorithm: One-Third Rule

#### Initialization

 $x_p := v_p$ ,  $decide_p := null$   $(v_p : initial value of p)$ 

#### For each round $r\geq 0$

 $S_p^r$ : send  $x_p$  to all processes

 $T_p^r$ : if |HO(p,r)| > 2N/3 then

set  $x_p$  to smallest among the most frequently received values if more than 2N/3 values received are equal to  $x_p$  then  $decide_p := x_p$ 

#### Simple but efficient consensus algorithm

- no coordinator needed
- quick convergence if few errors

# Representing executions of HO algorithms

- Fine-grained execution for HO collection (HO(p, r))<sub>p∈Proc,r∈ℕ</sub>
  - message receptions, local transitions, message sending
  - verify correctness for all HO collections

```
process Node(p \in Proc)

state st = s_{0,p};

integer r = 0;

for q \in Proc do send(p,q,r, S_p^r(st,q)) enddo;

loop

array rcvd = [q \in Proc \mapsto null];

for q \in HO(p,r) do rcvd[q] := receive(q,p,r) enddo;

st, r := T_p^r(st, rcvd), r + 1;

for q \in Proc do send(p,q,r, S_p^r(st,q)) enddo;

end loop

end process
```

• Formally: infinite sequence  $\xi = c_0 c_1 \dots$  of configurations

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- Formally: infinite sequence  $\xi = c_0 c_1 \dots$  of configurations
- Infinite-state model, due to round numbers



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### First reduction

- Remember left and right movers?
  - send actions are left movers
  - receive actions are right movers

(assuming infinite network capacity)

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#### • This motivates the following reduction:

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end loop

end process
```

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### More reduction

#### • Processes execute rounds atomically

init	init <mark>rnd 0</mark>	init	rnd 0	rnd 1	rnd 0	rnd 1	rnd 2	rnd 1	
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• Can we do any better?

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- Can we do any better?
- Remember communication-closed rounds
  - round  $rnd_p^m$  right-commutes with  $rnd_q^n$  if m > n
  - messages sent during rnd<sup>n</sup><sub>q</sub> did not influence rnd<sup>m</sup><sub>p</sub>
- Rearrange execution so that executions of same round are adjacent

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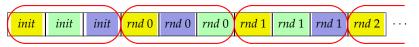
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- Rearrange execution so that executions of same round are adjacent



• Executions of same round by different processes are independent

# Coarse-grained model of executions

- Unit of atomicity: entire system rounds
  - all processes simultaneously perform transition for same round
  - corresponds to "nice" executions in the fine-grained model
- Coarse-grained execution  $\sigma_0 \sigma_1 \dots (\sigma_i : Proc \rightarrow State)$

• 
$$\sigma_0(p) = s_{0,p}$$
  
•  $\sigma_{r+1}(p) = T_p^r(\sigma_r(p), rcvd(p, r))$   
where  $rcvd(p, r) = [q \in HO(p, r) \mapsto S_q^r(\sigma_r(q), p)]$ 

#### • Coarse abstraction of distributed execution

- no need for explicit representation of network
- no round numbers: "synchronized" processes

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### $\Rightarrow$ How exactly does the reduced model relate to the original one?

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## Relating fine- and coarse-grained executions

- Fine-grained model contains more detail
- Compare executions w.r.t. the "local views" of processes
  - *p*-view of fine-grained execution  $\xi = c_0 c_1 \dots$

 $\xi^p = c_0.st(p), c_1.st(p), \dots$ 

• *p*-view of coarse-grained execution  $\sigma = \sigma_0 \sigma_1 \dots$ 

 $\sigma^p = \sigma_0(p), \sigma_1(p), \ldots$ 

- *p*-views are sequences of states of *p* and can be compared
- Executions equivalent iff indistinguishable by any process

 $\xi \approx \sigma$  iff  $\natural(\xi^p) = \natural(\sigma^p)$  for every  $p \in Proc$ 

local views equal up to stuttering, for every process

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### Reduction theorem

#### Theorem (Reduction)

Given a HO collection (HO(p, r)) and a fine-grained execution  $\xi$  there exists a coarse-grained execution  $\sigma$  for the same HO collection such that  $\sigma \approx \xi$ .

**Proof.** For  $\xi = c_0 c_1 \dots$ , define sequence  $\sigma = ([p \in Proc \mapsto c_{\ell_r^p} . st(p)])_{r \in \mathbb{N}}$ where  $\begin{cases} \ell_0^p = 0 \\ \ell_{r+1}^p = k+1 & \text{if } (c_k, c_{k+1}) \text{ is } (r+1) \text{st local transition of } p. \end{cases}$ Then  $\sigma$  is a coarse-grained execution for the same HO collection. Moreover,  $\natural(\sigma^p) = \natural(\xi^p)$  for all  $p \in Proc$ . Q.E.D.

#### • Converse theorem is trivially true

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# "Local" properties

- Application of reduction theorem to verification
  - many properties depend only on local views
  - these can be verified by considering only coarse-grained executions
- Local properties *P* of executions

 $\rho_1 \models P$  iff  $\rho_2 \models P$  whenever  $\rho_1 \approx \rho_2$ 

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# "Local" properties

- Application of reduction theorem to verification
  - many properties depend only on local views
  - these can be verified by considering only coarse-grained executions
- Local properties *P* of executions

 $\rho_1 \models P \quad \text{iff} \quad \rho_2 \models P \qquad \text{whenever } \rho_1 \approx \rho_2$ 

- The following LTL-X properties are local
  - ► formulas *Q*(*p*) built solely from *p*'s state variables
  - arbitrary first-order combinations of local properties
  - **but:** temporal combinations need not be local, consider:

 $\bigwedge_{p,q\in Proc} \Box(rnd_p = rnd_q) \qquad \text{(where } rnd_p \text{ is the current round of } p)$ 

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# Consensus as a local property

• Integrity

$$\bigwedge_{p \in Proc} \forall v \neq null : \left( \Diamond (decide_p = v) \Rightarrow \bigvee_{q \in Proc} x_q = v \right)$$

• Irrevocability

$$\bigwedge_{p \in Proc} \forall v \neq null : \Box(decide_p = v \Rightarrow \Box(decide_p = v))$$

• Agreement

$$\bigwedge_{p,q\in Proc} \forall v, w \neq null : \Diamond (decide_p = v) \land \Diamond (decide_q = w) \Rightarrow v = w$$

#### • Termination

$$\bigwedge_{p \in Proc} \Diamond (decide_p \neq null)$$

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#### 5 Conclusion

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## Finite-state model checking

- Verification of finite instances of algorithms
  - model coarse-grained executions for fixed number of processes
  - non-deterministic choice of HO sets at every transition
  - resulting model is finite-state
- Generic TLA<sup>+</sup> module *HeardOf* 
  - high-level definition of coarse-grained HO semantics
  - pre-define useful communication predicates
  - concrete algorithms obtained later as instances

#### • Here: favor clarity over efficiency

# Generic TLA<sup>+</sup> module

- MODULE HeardOf EXTENDS Naturals CONSTANTS Proc, State, Msg, nPhases, IniSt(\_), Send(\_, \_, \_, \_), Trans(\_, \_, \_, \_) VARIABLES phase, state, heardof  $\triangleq$ Init  $\wedge$  *phase* = 0  $\wedge$  state = [ $p \in Proc \mapsto IniSt(p)$ ]  $\land$  heard of = [ $p \in Proc \mapsto \{\}$ ]  $\stackrel{\triangle}{=} \text{ LET } rcvd(p) \stackrel{\triangle}{=} \{ \langle q, Send(q, phase, state[q], p) \rangle : q \in HO[p] \}$ Step(HO) $\wedge$  phase' = (phase + 1) % nPhases IN  $\land$  state' = [ $p \in Proc \mapsto Trans(p, phase, state[p], rcvd(p))$ ]  $\wedge$  heard of ' = HO $\triangleq$  $\exists HO \in [Proc \rightarrow SUBSET Proc] : Step(HO)$ Next  $\stackrel{\triangle}{=}$  $\forall p, q \in Proc : HO[p] \cap HO[q] \neq \{\}$ NoSplit(HO)  $\triangleq$ *NextNoSplit*  $\exists HO \in [Proc \rightarrow SUBSET Proc] : NoSplit(HO) \land Step(HO)$  $\triangleq$  $\exists S \in \text{SUBSET } Proc : HO = [q \in Proc \mapsto S]$ *Uniform*(*HO*)  $\triangleq$ *InfiniteUniform*  $\Box \Diamond Uniform(heard of)$ 

### Remarks

- Definitions closely parallels "paper" version
  - expressiveness of TLA<sup>+</sup> leads to perspicuous formulation
  - (auxiliary) variable *heardof* records HO sets during a run
  - mainly used for debugging and printing counter-examples
- Formulation of communication predicates
  - safety predicates: add to next-state relation
  - liveness predicates: natural expression in temporal logic
  - used to express correctness properties

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# One-Third Rule in $TLA^+$ (1/3)

MODULE OneThirdRule						
nPhases	$\stackrel{\vartriangle}{=}$	1				
Proc	$\stackrel{\triangle}{=}$	1 <i>N</i>				
InitValue(p)	$\stackrel{\triangle}{=}$	10 * <i>p</i>				
Value	$\stackrel{\triangle}{=}$	$\{InitValue(p): p \in Proc\}$				
Msg	$\stackrel{\vartriangle}{=}$	Value				
null	$\stackrel{\vartriangle}{=}$	0				
ValueOrNull	$\stackrel{\triangle}{=}$	$Value \cup \{null\}$				
State		[x : Value, decide : ValueOrNull]				

- definition of constant parameters for OneThirdRule algorithm
- arbitrary definition of (initial) values of a process

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## One-Third Rule in $TLA^+$ (2/3)

 $\stackrel{\triangle}{=} [x \mapsto InitValue(p), decide \mapsto null]$ IniSt(p)Send $(p, ph, s, q) \stackrel{\triangle}{=} s.x$  $Trans(p, ph, s, rcvd) \stackrel{\triangle}{=}$ IF Cardinality(rcvd) >  $(2 * N) \div 3$ THEN LET  $Freq(v) \stackrel{\triangle}{=} Cardinality(\{q \in Proc : \langle q, v \rangle \in rcvd\})$  $MFR(v) \stackrel{\triangle}{=} \forall w \in Value : Freq(w) < Freq(v)$  $min \stackrel{\triangle}{=} CHOOSE v \in Value : MFR(v) \land \forall w \in Value : MFR(w) \Rightarrow v \leq w$ IN  $[x \mapsto min,$ *decide*  $\mapsto$  IF *Freq*(*min*) > (2 \* N)  $\div$  3 THEN *min* ELSE *s.decide*] ELSE S

INSTANCE *HeardOf* 

- definition of the send and state transition functions
- instantiation of generic module

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# One-Third Rule in $TLA^+$ (3/3)

Safety	Δ	$Init \wedge \Box [Next]_{vars}$				
5 0						
Liveness		$\Box \Diamond (\textit{Uniform}(\textit{heardof}) \land \textit{Cardinality}(\textit{heardof}) > (2 * N) \div 3)$				
Integrity	<u>∆</u>	$\forall p \in Proc : state[p].decide \in ValueOrNull$				
Irrevocability	$\stackrel{\scriptscriptstyle \bigtriangleup}{=}$	$\forall p \in Proc : \Box[state[p].decide = null]_{state[p].decide}$				
Agreement	$\stackrel{\scriptscriptstyle \Delta}{=}$	$\forall p, q \in Proc : (state[p].decide \neq null \land state[q].decide \neq null$				
		$\Rightarrow$ state[p].decide = state[q].decide)				
Termination	$\stackrel{\scriptscriptstyle \Delta}{=}$	$\forall p \in Proc : \Diamond(state[p].decide \neq null)$				
THEOREM Safety $\Rightarrow \Box(Integrity \land Agreement) \land Irrevocability$						
THEOREM Safety $\land$ Liveness $\Rightarrow$ Termination						

#### • definition of correctness properties

• formulation of correctness theorems, under precise hypotheses

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## Results of verification

	OneT	hirdRule	UniformVoting	
	N = 3	N = 4	<i>N</i> = 3	N = 4
states	5633	9,830,401	21,351	15,865,770
distinct	11	150	122	887
time (s)	1.87	939	13.8	1330

- Model checking feasible for small instances
  - high branching factor: exploration of all HO collections
  - many redundant states generated
- Symbolic model checking can be more efficient
  - more complicated encodings necessary for tools like NuSMV
  - cf. work by Tsuchiya and Schiper: Paxos for 10 processes

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# Verification in Isabelle/HOL

### Similar overall model

- main difference: introduction of types
- generic *HeardOf* module represented as an Isabelle locale

```
locale HOAlgorithm =

fixes

nPhases :: nat and

iniSt :: 'proc \rightarrow 'pst and

send :: 'proc \rightarrow nat \rightarrow 'pst \rightarrow 'proc \rightarrow 'msg and

trans :: 'proc \rightarrow nat \rightarrow 'pst \rightarrow ('proc \rightarrow 'msg) \rightarrow 'pst

assumes

nSteps : 0 < nPhases and

finiteProc : finite(UNIV :: 'procset)
```

- defines generic behavior of HO algorithms
- proves useful rules, such as induction over executions

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### Proof of correctness

- Validity: standard invariance proof
- Irrevocability and agreement via sequence of lemmas
  - if process decides on value v then more than 2N/3 processes contain v in their x field
  - if more than 2N/3 processes send v and process p hears from more than 2N/3 processes then p updates its x field to v
  - Whenever process has decided on v then more than 2N/3 processes contain v in their x field
  - hence, processes cannot decide on different values
- Liveness: symbolically execute uniform rounds

## Proof of correctness

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  - Whenever process has decided on v then more than 2N/3 processes contain v in their x field
  - hence, processes cannot decide on different values
- Liveness: symbolically execute uniform rounds
- Proof lengths in Isar (including model and explanations)
  - ▶ 8 pages for generic module and lemmas
  - ▶ 8 pages for *OneThirdRule*
  - > 25 pages for *LastVoting* (cf. 130 pages for fine-grained model!)

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### Reduction Theorems for the Verification of Concurrent Programs

- 2 Fault-Tolerant Distributed Computing
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# Reduction: a revival?

#### • Recast of classical theorems

- identify left and right movers for coarser unit of atomicity
- distributed algorithms present interesting opportunities
- substantial reduction of verification effort possible

### • Transcend historical formulations

- beyond programming-language based presentations
- wide interpretation of "processes" (e.g., set of rounds)
- verify safety and liveness properties

### • Ongoing / future work

- establish more general reduction theorems
- better syntactic characterization of local properties
- implementation of reduction in verification tools