Computability, Randomness and Ergodic Theory on Metric Spaces

(Calculabilité, aléatoire et théorie ergodique sur les espaces métriques)

Mathieu Hoyrup

ENS

June 17, 2008

1 What does randomness look like?

- 1 What does randomness look like?
- 2 How does randomness appear?

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1. Probability theory

What properties should random sequences satisfy?

- What does randomness look like?
- 2 How does randomness appear?

1. Probability theory

What properties should random sequences satisfy?

Strong law of large numbers

In random sequences, number of 0's = number of 1's.

- What does randomness look like?
- 2 How does randomness appear?

2. Ergodic theory

In deterministic dynamical systems, as unpredictability.

- Space X,
- Transformation $T: X \rightarrow X$.



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- Space X,
- Transformation $T: X \rightarrow X$,



... observed with sharp eyes

- Space X,
- Transformation $T: X \rightarrow X$,
- Laplace's demon.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



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 $S_0, S_1, S_2, S_3, S_4, \ldots$

Deterministic dynamical systems probabilistic point of view

- Space X,
- Transformation $T: X \rightarrow X$,
- Invariant measure μ .



What does randomness look like?

1. Probability theory

What properties should random sequences satisfy?

Algorithmic randomness (Martin-Löf, 1966)

 $\{0,1\}^{\mathbb{N}}=R_{\mu}\uplus N_{\mu}$

000000000000000000000000...

001110011100111001...

01010001011011011100110 . . .

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Comput., Rand. and Ergodic Theory

What does randomness look like?
How does randomness appear?

2. Ergodic theory

In deterministic dynamical systems, as unpredictability.

Algorithmic complexity of orbits (Kolmogorov, 1965 – Brudno, 1978)

"A system is unpredictable

\Leftrightarrow

its orbits are algorithmically unpredictable"

Computability, Randomness and Ergodic Theory on Metric Spaces.

- Study of algorithmic randomness on general spaces,
- Development of algorithmic probability theory,
- Contributions to algorithmic complexity of orbits, relations with algorithmic randomness.

Computability/Semi-computability

2 Algorithmic randomness

- Random sequences
- Random points in metric spaces

3 Computability on probability spaces

- Computability theory is topological
- Definitions
- Existence of almost decidable sets

4 Complexity of dynamical systems

- Classical setting
- Orbit complexity
- Topological relations

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$\underset{\text{on }\mathbb{R}}{\textbf{Computability}/\text{Semi-computability}}$

Fast convergence: $q_i \rightarrow x$ means $d(q_i, x) < 2^{-i}$.



$\underset{\text{on }\mathbb{R}}{\textbf{Computability}/\text{Semi-computability}}$

Fast convergence: $q_i \rightarrow x$ means $d(q_i, x) < 2^{-i}$.



Computable function
$$f: \mathbb{R} \to \mathbb{R}$$

$$q_i \rightarrow x$$
 algorithm $q'_i \rightarrow f(x)$

Examples

- Computable real numbers: $\sqrt{2}, \pi, e, \text{etc.}$
- Computable real functions: \sqrt{x} , cos, ln, etc.

$\underset{\text{on }\mathbb{R}}{\text{Computability}}/\text{Semi-computability}$

Lower convergence: $q_i \nearrow x$ means $q_i \le q_{i+1}, q_i \rightarrow x$.



Lower semi-computable function $f : \mathbb{R} \to \mathbb{R}$

$$q_i \rightarrow x$$
 algorithm $q'_i \nearrow f(x)$

Example

• Lower semi-computable real function: $\mathbf{1}_{(0,1)}$

$\mathbb{R}_{c} = \{ \text{computable real numbers} \}$ $\mathbb{R}_{sc} = \{ \text{semi-computable real numbers} \}$

Both \mathbb{R}_{c} and \mathbb{R}_{sc} are countable. But...

Computability

 \mathbb{R}_{c} is "effectively uncountable"

Semi-computability

 \mathbb{R}_{sc} is "effectively countable"

Computability/Semi-computability

Abstract structures

 $q_i \rightarrow x$ means $d(q_i, x) < 2^{-i}$.

 $q_i \nearrow x$ means $q_i \le q_{i+1}, q_i \to x$.

Computability/Semi-computability Abstract structures

 $q_i \rightarrow x$ means $d(q_i, x) < 2^{-i}$.

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Computable metric space

to express computability

Enumerative lattice

to express semi-computability

Computability/Semi-computability

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Computable metric space

to express computability

- Rⁿ, euclidean distance,
- C([0, 1]), uniform distance ||.||∞,
- Compact subsets of ℝ, Hausdorff distance,

Enumerative lattice

to express semi-computability

- $\overline{\mathbb{R}}$, order \leq ,
- $\mathcal{P}(\mathbb{N})$, order \subseteq ,
- X computable metric space:
 - τ_X , order \subseteq ,
 - $LC(X, \overline{\mathbb{R}})^a$, order \leq .

^acalled $\mathcal{C}(X, \overline{\mathbb{R}})$ in the thesis.
Computability/Semi-computability

Abstract structures

$$q_i \rightarrow x$$
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Computable metric space

to express computability

- Rⁿ, euclidean distance,
- C([0, 1]), uniform distance ||.||∞,
- Compact subsets of ℝ, Hausdorff distance,
- *M*(*X*),
 Prokhorov distance.

Enumerative lattice

to express semi-computability

- $\overline{\mathbb{R}}$, order \leq ,
- $\mathcal{P}(\mathbb{N})$, order \subseteq ,
- X computable metric space:
 - τ_X , order \subseteq ,
 - $LC(X, \overline{\mathbb{R}})^a$, order \leq .

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Computability/Semi-computability

Computable probability measure

Theorem (2.1.4.1)

Let $\mu \in \mathcal{M}(X)$ be a probability measure.

 μ is computable \iff all $\mu(B_1 \cup \ldots \cup B_n)$ are lower semi-computable.



$\overline{\mathsf{On}}\ \mathbb{R}$

 μ is computable \iff all $\mu(q_1, q_2)$ are lower semi-computable.

On $\{0,1\}^{\mathbb{N}}$

 μ is computable \iff all $\mu([w])$ are computable ($w \in \{0,1\}^*$).

Computability/Semi-computability

Abstract structures

Computable metric space

to express computability

Enumerative lattice

to express semi-computability

The set of computable objects is "effectively uncountable" (in general) The set of semi-computable objects is "effectively countable"

Computability/Semi-computability

2 Algorithmic randomness

- Random sequences
- Random points in metric spaces

3 Computability on probability spaces

- Computability theory is topological
- Definitions
- Existence of almost decidable sets

4 Complexity of dynamical systems

- Classical setting
- Orbit complexity
- Topological relations

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 μ (computable) probablity measure on $\{0,1\}^{\mathbb{N}}$

Definition (Martin-Löf, 1966)

A sequence ω is μ -random if it withstands all μ -tests.

```
\mu (computable) probablity measure on \{0,1\}^{\mathbb{N}}
```

Definition (Martin-Löf, 1966)

- A μ -test is a function $t: \{0,1\}^{\mathbb{N}} \to [0,+\infty]$ such that:
 - $\int t \,\mathrm{d}\mu < \infty,$
 - **2** t is lower semi-computable.

Definition (Martin-Löf, 1966)

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Definition (Martin-Löf, 1966)

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 - 2 t is lower semi-computable.

A sequence ω withstands the test if $t(\omega) < \infty$.

Definition (Martin-Löf, 1966)

A sequence ω is μ -random if it withstands all μ -tests.

Algorithmically random sequences

Application to probability theory

Definition

A property *P* is testable if there is a μ -test *t* such that:

 $t(\omega) < \infty \implies P(\omega)$ holds.

 $P(\omega)$ holds for μ -almost every sequence ω

becomes

 $P(\omega)$ holds for every μ -random sequence ω .

Examples

Strong law of large numbers, law of the iterated logarithm, etc.

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Comput., Rand. and Ergodic Theory

Algorithmically random sequences Martin-Löf, 1966

Theorem (Martin-Löf, 1966)

There is a universal μ -test **t**:

 ω is μ -random $\iff \omega$ withstands **t**.

This test can be expressed in terms of Kolmogorov complexity.

Algorithmically random sequences

Binary sequences

- Kolmogorov,
- Martin-Löf, 1966,
- Levin,
- Chaitin,
- Schnorr,
- Gács,
- V'yugin,
- Vovk,
- Asarin,
- Van Lambalgen,
- Downey,
- Hirschfeldt,
- Li,
- Vitanyi,
- Miller,

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More general objects

- Asarin, 1986.
 Random functions (Brownian motion).
- Barmpalias et al., 2007.
 Random closed subsets of {0,1}^ℕ.

Abstract spaces

- Weihrauch, Hertling, 1998. Topological spaces.
- Gács, 2005.

Metric spaces.

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Definition (Martin-Löf, 1966)

- A μ -test is a function $t: \{0,1\}^{\mathbb{N}} \to [0,+\infty]$ satisfying:

 - 2 t is lower semi-computable.

A sequence ω withstands the test *t* if $t(\omega) < \infty$.

Definition (Martin-Löf, 1966)

A sequence ω is μ -random if it withstands all μ -tests t.

Algorithmic randomness: extensions Martin-Löf, 1966 ~ Gács, 2005

First extension: space $\{0,1\}^{\mathbb{N}} \longrightarrow \text{computable metric space } X$ sequence $\omega \longrightarrow \text{point } x$ Definition (Martin-Löf, 1966) A μ -test is a function $t : \{0,1\}^{\mathbb{N}} \rightarrow [0,+\infty]$ satisfying: 1) $\int t \, d\mu < +\infty$, 2) t is lower semi-computable. A sequence ω withstands the test t if $t(\omega) < \infty$.

Definition (Martin-Löf, 1966)

A sequence ω is μ -random if it withstands all μ -tests t.

First extension:space $\{0,1\}^{\mathbb{N}} \rightarrow$ \rightsquigarrow computable metric space Xsequence $\omega \rightarrow$ point x

Definition (Martin-Löf, 1966 – Gács, 2005)

A μ -test is a function $t: X \to [0, +\infty]$ satisfying:

2 t is lower semi-computable.

A point x withstands the test t if $t(x) < \infty$.

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A point x withstands the test t if $t(x) < \infty$.

Definition (Martin-Löf, 1966 – Gács, 2005)

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- A uniform test is a function $T : \mathcal{M}(X) \times X \to [0, +\infty]$ such that:

 - **2** *t* is lower semi-computable.

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A uniform test is a function $T : \mathcal{M}(X) \times X \to [0, +\infty]$ such that:

- $\ \ \, \mathbf{0} \ \ \, \int \mathcal{T}_\mu \, \mathrm{d} \mu < \infty \ \text{for each} \ \ \, \mu \in \mathcal{M}(X) \qquad \text{(where } \ \ \, \mathcal{T}_\mu(.) = \mathcal{T}(\mu,.)\text{)},$
- (2) t is lower semi-computable.

A point x withstands the test t if $t(x) < \infty$.

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- **2** T is lower semi-computable.

A point x withstands the test T_{μ} if $T_{\mu}(x) < \infty$.

Definition (Martin-Löf, 1966 – Gács, 2005)

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A uniform test is a function $T : \mathcal{M}(X) \times X \to [0, +\infty]$ such that:

- 1) $\int T_{\mu} d\mu < \infty$ for each $\mu \in \mathcal{M}(X)$ (where $T_{\mu}(.) = T(\mu,.)$),
- **2** T is lower semi-computable.

A point x withstands the test T_{μ} if $T_{\mu}(x) < \infty$.

Definition (Martin-Löf, 1966 – Gács, 2005)

Martin-Löf, 1966 ~> Gács, 2005

Computable metric space X.

Theorem (Gács, 2005)

There is a universal uniform test $T : \mathcal{M}(X) \times X \to [0, +\infty]$:

a point x is μ -random \iff x passes the test \mathbf{T}_{μ} .

Martin-Löf, 1966 ~> Gács, 2005

Computable metric space X.

Theorem (Gács, 2005)

Suppose X satisfies the Boolean inclusion property. There is a universal uniform test $T : \mathcal{M}(X) \times X \to [0, +\infty]$:

a point x is μ -random \iff x passes the test \mathbf{T}_{μ} .

Martin-Löf, 1966 ~> Gács, 2005

Computable metric space X.

Theorem (Gács, 2005)

Suppose X satisfies the Boolean inclusion property. There is a universal uniform test $\mathbf{T} : \mathcal{M}(X) \times X \to [0, +\infty]$:

a point x is μ -random \iff x passes the test \mathbf{T}_{μ} .

Theorem

The Boolean inclusion property is not necessary. Every computable metric space admits a universal uniform test.

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Theorem

The Boolean inclusion property is not necessary. Every computable metric space admits a universal uniform test.

Let μ be a probability measure on X, and $t: X \to [0, +\infty]$ a μ -test:

Martin-Löf, 1966 ~> Gács, 2005

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Theorem (Gács, 2005)

Suppose X satisfies the Boolean inclusion property. There is a universal uniform test $\mathbf{T} : \mathcal{M}(X) \times X \to [0, +\infty]$:

a point x is μ -random \iff x passes the test \mathbf{T}_{μ} .

Theorem

The Boolean inclusion property is not necessary. Every computable metric space admits a universal uniform test.

Let μ be a probability measure on X, and $t: X \to [0, +\infty]$ a μ -test:

Theorem (μ -tests versus uniform tests)

There is a uniform test $T : \mathcal{M}(X) \times X \to [0, +\infty]$ such that $T_{\mu} = t$.

Probabilistic statement:

$$P(\omega)$$
 holds for μ -almost every sequence ω

becomes

 $P(\omega)$ holds for every μ -random sequence ω

Examples

Strong law of large numbers, law of the iterated logarithm, etc.

Probabilistic statement:

$$R(x)$$
 holds for μ -almost every point x

becomes

R(x) holds for every μ -random point x

Examples

Birkhoff ergodic theorem, Shannon-McMillan-Breiman theorem, convergence of random variables, etc.

Computability/Semi-computability

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- Computability theory is topological
- Definitions
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4 Complexity of dynamical systems

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Theorem

On \mathbb{R} , every computable function is continuous.

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Theorem

Representing real numbers by their binary expansion is not suitable.

$$\frac{bin(x)}{algorithm} \xrightarrow{bin(f(x))}$$

It makes the function $x \mapsto 3x$ non-computable.

Theorem

On \mathbb{R} , every computable function is continuous.

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Theorem

Representing real numbers by their binary expansion is not suitable.

$$\frac{bin(x)}{algorithm} \xrightarrow{bin(f(x))}$$

It makes the function $x \mapsto 3x$ non-computable.

Proof. [0, 1] and $\{0, 1\}^{\mathbb{N}}$ are not homeomorphic. Mathieu Hoyrup (ENS) Comput., Rand. and Ergodic Theory June 17, 2008 32 / 59


Computability theory is topological



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Definition (2.2.0.1)

 (X, μ) is a computable probability space if:

- X is a computable metric space,
- μ is a computable probability measure on X.

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Definition (attempt...)

 $f: X \to Y$ is almost computable if it is computable on a set A satisfying $\mu(A) = 1$.

Definition (2.2.0.1)

(X, μ) is a computable probability space if:

- X is a computable metric space,
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Definition (attempt...)

 $f: X \to Y$ is almost computable if it is computable on a set A satisfying $\mu(A) = 1$.

Theorem (1.6.2.1)

Let $f : X \to Y$ be an almost computable function. There is a function g which coincides with f on A, and is computable on a constructive G_{δ} -set containing A.

Definition (2.2.0.1)

(X, μ) is a computable probability space if:

- X is a computable metric space,
- μ is a computable probability measure on X.

Definition (2.2.0.2)

 $f: X \to Y$ is almost computable if it is computable on a constructive G_{δ} -set A satisfying $\mu(A) = 1$.

Theorem (1.6.2.1)

Let $f : X \to Y$ be an almost computable function. There is a function g which coincides with f on A, and is computable on a constructive G_{δ} -set containing A.

Definition (2.2.1.2)

A set $A \subseteq X$ is almost decidable if the function $1_A : X \to \{0, 1\}$ is almost computable.

On \mathbb{R}

Interval $[x_1, x_2]$ with x_1, x_2 computable and $\mu(x_1) = \mu(x_2) = 0$.

Definition (2.2.1.2)

A set $A \subseteq X$ is almost decidable if the function $1_A : X \to \{0, 1\}$ is almost computable.

On \mathbb{R}

Interval $[x_1, x_2]$ with x_1, x_2 computable and $\mu(x_1) = \mu(x_2) = 0$.

Proposition (2.2.1.1)

If μ is computable and A is almost decidable, then $\mu(A)$ is computable.

Definition (2.2.1.2)

A set $A \subseteq X$ is almost decidable if the function $1_A : X \to \{0, 1\}$ is almost computable.

$\mathsf{On}\ \mathbb{R}$

Interval $[x_1, x_2]$ with x_1, x_2 computable and $\mu(x_1) = \mu(x_2) = 0$.

Proposition (2.2.1.1)

If μ is computable and A is almost decidable, then $\mu(A)$ is computable.

Definition (2.2.0.2)

A morphism $f : (X, \mu) \to (Y, \nu)$ is an almost computable function $f : X \to Y$ which maps μ to ν (i.e. $\nu = \mu f^{-1}$).

Algorithmic probability theory and Random points

Theorem

When restricting to random points,

	$On(X,\mu) \longrightarrow$	$On(R_{\mu},\mu)$
function	almost computable	computable
set	almost decidable	decidable
sequence	effective a.e. convergence	pointwise convergence

Proposition (3.2.0.8)

- Morphisms preserve randomness.
- Isomorphisms, when restricted to random points, are computable homeomorphisms.

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Existence of almost decidable sets

X = [0, 1], μ computable probability measure.

Question

Is it possible that $\mu(\{x\}) \neq 0$ for all computable x ?



Existence of almost decidable sets

X = [0, 1], μ computable probability measure.

Question

Is it possible that $\mu({x}) \neq 0$ for all computable x ?





Existence of almost decidable sets

X = [0, 1], μ computable probability measure.

Question

Is it possible that $\mu({x}) \neq 0$ for all computable x ?



Theorem (2.2.1.2)

No. There is a computable dense sequence of μ -continuity points.

Existence of almost decidable sets

X = [0, 1], μ computable probability measure.

Question

Is it possible that $\mu({x}) \neq 0$ for all computable x ?



Theorem (2.2.1.2)

No. There is a computable dense sequence of μ -continuity points.

Proof.

Application of: " \mathbb{R}_c is effectively uncountable".

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Comput., Rand. and Ergodic Theory

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 (X, μ) computable probability space.

Theorem (2.2.1.2)

There is a basis of almost decidable balls.

 (X, μ) computable probability space.

Theorem (2.2.1.2)

There is a basis of almost decidable balls.

Theorem (2.2.1.1)

 (X, μ) admits a generalized binary representation.

 (X, μ) computable probability space.

Theorem (2.2.1.2)

There is a basis of almost decidable balls.

Theorem (2.2.1.1)

 (X, μ) admits a generalized binary representation.

Theorem (2.2.2.1)

When μ has no mass point, (X, μ) is isomorphic to $(\{0, 1\}^{\mathbb{N}}, Lebesgue)$.

 (X, μ) computable probability space.

Theorem (2.2.1.2)

There is a basis of almost decidable balls.

Theorem (2.2.1.1)

 (X, μ) admits a generalized binary representation.

Theorem (2.2.2.1)

When μ has no mass point, (X, μ) is isomorphic to $(\{0, 1\}^{\mathbb{N}}, Lebesgue)$.

Applications

Transfer of algorithmic randomness, computable symbolic models.

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Computability/Semi-computability

2 Algorithmic randomness

- Random sequences
- Random points in metric spaces

3 Computability on probability spaces

- Computability theory is topological
- Definitions
- Existence of almost decidable sets

Complexity of dynamical systems
Classical setting

- Orbit complexity
- Topological relations

- Space X,
- Transformation $T: X \rightarrow X$.



- Space X,
- Transformation $T: X \rightarrow X$,
- Laplace's demon.



- Space X,
- Transformation $T: X \rightarrow X$,
- Laplace's demon.



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- Transformation $T: X \rightarrow X$,
- Laplace's demon.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



*s*₀, *s*₁, *s*₂, *s*₃

- Space X,
- Transformation $T: X \rightarrow X$,
- Precision $\epsilon > 0$.



 $s_0, s_1, s_2, s_3, s_4, \ldots$

Observing a dynamical system... ...through a partition

- Space X,
- Transformation $T: X \rightarrow X$,
- Partition $P = \{A, B, C, D\}$.



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Topological point of view

Probabilistic point of view

Topological system:

- X compact topological space,
- $T: X \to X$ continuous.



Ergodic dynamical system:

- (X, μ) probability space,
- $T: X \rightarrow X$ ergodic endomorphism.



Topological entropy h(T).

Measure-theoretic entropy $h_{\mu}(T)$.

Topological point of view

Probabilistic point of view

h(T) $h_{\mu}(T)$

Topological point of view

Probabilistic point of view

$$h(T) \xleftarrow{\text{variational}}{principle} h_{\mu}(T)$$

Theorem (Variational principle)

(X, T) topological dynamical system:

$$h(T) = \sup_{\mu \text{ invariant}} h_{\mu}(T)$$

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Algorithmic point of view

- Space X,
- Transformation $T: X \rightarrow X$.



K(x, T): algorithmic complexity of the orbit of x under T.

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Observing a dynamical system...

 \ldots with finite precision

...through a partition

• (X, T) topological system,

(X, μ, T) ergodic dynamical system





 $\mathcal{K}_n(x,T)$

 $\mathcal{K}_n(x,T)$

Observing a dynamical system...

 \ldots with finite precision

...through a partition

- (X, T) topological system,
- precision $\epsilon > 0$.



- (X, μ, T) ergodic dynamical system
- partition $P = \{A, B, C, D\}$



 $\mathcal{K}_5(x, T|P) = K(\mathsf{CBABA})$

 $\mathcal{K}_5(x, T, \epsilon) = \mathcal{K}(s_0, s_1, s_2, s_3, s_4)$

Orbit complexity ...with finite precision

...through a partition

(X, T) topological system

$$\overline{\mathcal{K}}(x, T, \epsilon) = \overline{\lim}_n \frac{\mathcal{K}_n(x, T, \epsilon)}{n}$$

 $\underline{\mathcal{K}}(x, T, \epsilon) = \underline{\lim}_n \frac{\mathcal{K}_n(x, T, \epsilon)}{n}$

 (X, μ, T) ergodic system $\overline{\mathcal{K}}(x, T|P) = \overline{\lim}_n \frac{\mathcal{K}_n(x, T|P)}{n}$

$$\underline{\mathcal{K}}(x, T|P) = \underline{\lim}_n \frac{\mathcal{K}_n(x, T|P)}{n}$$

Orbit complexity ...with finite precision

...through a partition

(X, T) topological system

$$\overline{\mathcal{K}}(x, T, \epsilon) = \overline{\lim}_n \frac{\mathcal{K}_n(x, T, \epsilon)}{n}$$

 $\underline{\mathcal{K}}(x, T, \epsilon) = \underline{\lim}_n \frac{\mathcal{K}_n(x, T, \epsilon)}{n}$

$$(X, \mu, T)$$
 ergodic system

 $\overline{\mathcal{K}}(x, T|P) = \overline{\lim}_n \frac{\mathcal{K}_n(x, T|P)}{n}$

$$\underline{\mathcal{K}}(x, T|P) = \underline{\lim}_n \frac{\mathcal{K}_n(x, T|P)}{n}$$

Definition (Galatolo, 2000 – generalizing Brudno, 1983)

$$\overline{\mathcal{K}}(x, T) = \sup_{\epsilon > 0} \overline{\mathcal{K}}(x, T, \epsilon)$$

$$\underline{\mathcal{K}}(x, T) = \sup_{\epsilon > 0} \underline{\mathcal{K}}(x, T, \epsilon)$$

$$\overline{\mathcal{K}}_{\mu}(x, T) = \sup_{\substack{P \text{ comp.} \\ P \text{ comp.}}} \overline{\mathcal{K}}(x, T|P)$$
$$\underline{\mathcal{K}}_{\mu}(x, T) = \sup_{\substack{P \text{ comp.} \\ P \text{ comp.}}} \underline{\mathcal{K}}(x, T|P)$$

probabilistic context



probabilistic context



Theorem (Brudno, 1978)

 (X, μ, T) ergodic dynamical system:

 $\overline{\mathcal{K}}_{\mu}(x,T) = h_{\mu}(T)$ for μ -almost every x

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probabilistic context



Theorem (5.1.4.2)

 (X, μ, T) computable ergodic dynamical system:

 $\overline{\mathcal{K}}_{\mu}(x, T) = h_{\mu}(T)$ for every μ -random x

probabilistic context



Theorem (5.1.4.2)

 (X, μ, T) computable ergodic dynamical system:

 $\underline{\mathcal{K}}_{\mu}(x,T) \stackrel{?}{=} \overline{\mathcal{K}}_{\mu}(x,T) = h_{\mu}(T)$ for every μ -random x



Theorem (Brudno, 1983 – White, 1993)

(X, T) topological dynamical system:

 $\underline{\mathcal{K}}(x,T) = \overline{\mathcal{K}}(x,T) = h_{\mu}(T)$ for μ -almost every x

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Theorem (5.3.0.3)

 (X, μ, T) computable ergodic dynamical system, with X compact:

$$\underline{\mathcal{K}}(x, T) = \underline{\mathcal{K}}_{\mu}(x, T)$$

for every μ -random x
 $\overline{\mathcal{K}}(x, T) = \overline{\mathcal{K}}_{\mu}(x, T)$

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Proof.

- Shannon-McMillan-Breiman theorem for random points,
- Birkhoff ergodic theorem for random points,
- both derived from V'yugin's results on $\{0,1\}^{\mathbb{N}},$ using computable partitions.

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Theorem (5.2.3.1)

(X, T) topological system:

$$\sup_{x} \underline{\mathcal{K}}(x, T) = \sup_{x} \overline{\mathcal{K}}(x, T) = h(T)$$

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Orbit complexity vs entropy Topological point of view

(X, T) topological system.

Upper-bound:

Theorem (Brudno)

For all x,

 $\overline{\mathcal{K}}(x,T) \leq h(T).$

The set of simple orbits is small.

Theorem (5.2.3.2)

Let
$$Y_{\alpha} = \{x : \underline{\mathcal{K}}(x, T) \leq \alpha\}.$$

 $h(T, Y_{\alpha}) \leq \alpha.$

Orbit complexity vs entropy Topological point of view

(X, T) topological system.

Upper-bound:The set of simple orbits is small.Theorem (Brudno)Theorem (5.2.3.2)For all x,
 $\overline{\mathcal{K}}(x, T) \leq h(T)$.Let $Y_{\alpha} = \{x : \underline{\mathcal{K}}(x, T) \leq \alpha\}$.
 $h(T, Y_{\alpha}) \leq \alpha$.

Corollary

$$h(T) = \sup_{x} \underline{\mathcal{K}}(x, T) = \sup_{x} \overline{\mathcal{K}}(x, T)$$

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- Structure dedicated to semi-computability,
- Pramework for computability and probabilities,
- **8** Integration of algorithmic randomness to general probability theory,
- ④ Results about algorithmic complexity of orbits, relations with algorithmic randomness.

Computability and measure

- Effective integration theory (Edalat, 2007) and randomness,
- Ocomputation models on "physical" spaces,
- 2 Algorithmic randomness
 - Particular applications (e.g. Asarin's work on random functions),
 - Characterization of randomness using Kolmogorov complexity on metric spaces,

Oynamical systems

- Computability of invariant measures,
- 2 Relations between algorithmic complexity and Lyapunov exponents,

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