

Computational Complexity of the GPAC

Amaury Pouly

Joint work with Olivier Bournez and Daniel Graça

April 10, 2014

- 1 Introduction
 - GPAC
 - Computable Analysis
 - Analog Church Thesis
 - Complexity
- 2 Toward a Complexity Theory for the GPAC
 - What is the problem
 - Computational Complexity (Real Number)
- 3 Conclusion

GPAC

General Purpose Analog Computer

- by Claude Shannon (1941)

GPAC

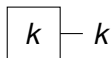
General Purpose Analog Computer

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- idealization of an analog computer: Differential Analyzer

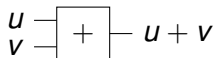
GPAC

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- circuit built from:



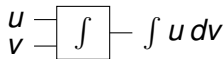
A constant unit



An adder unit



An multiplier unit



An integrator unit

GPAC: beyond the circuit approach

Theorem

y is generated by a GPAC iff it is a component of the solution $y = (y_1, \dots, y_d)$ of the Polynomial Initial Value Problem (PIVP):

$$\begin{cases} y' = p(y) \\ y(t_0) = y_0 \end{cases}$$

where p is a vector of polynomials.

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- continuous dynamical system

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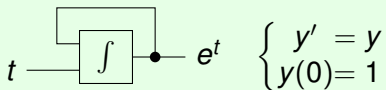
Remark

- continuous dynamical system
- the GPAC is just one reason to look at them^a

^aAsk question

GPAC: examples

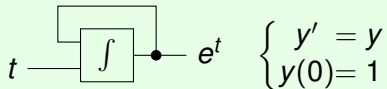
Example (One variable, linear system)



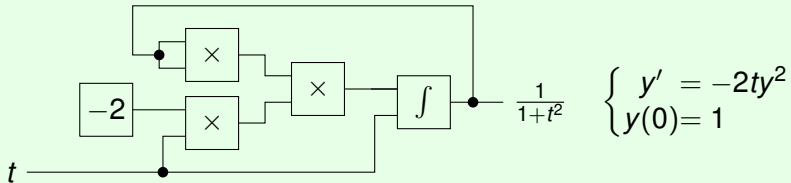
$$\begin{cases} y' = y \\ y(0) = 1 \end{cases}$$

GPAC: examples

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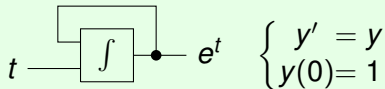


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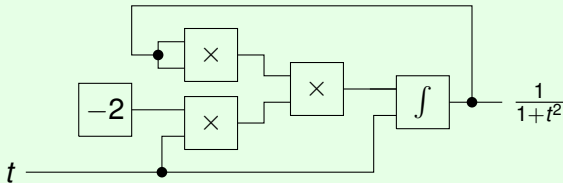


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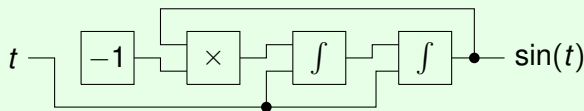


Example (Two variable, nonlinear system)



GPAC: examples

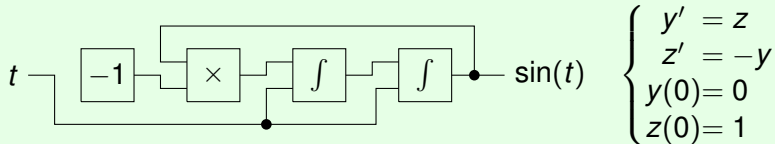
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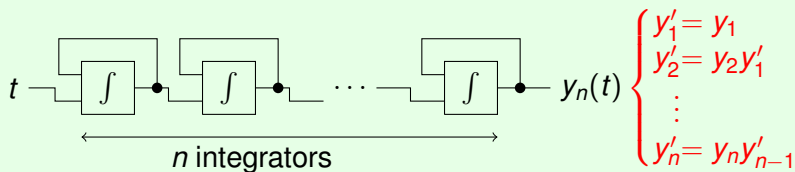
$$\begin{cases} y' = z \\ z' = -y \\ y(0) = 0 \\ z(0) = 1 \end{cases}$$

GPAC: examples

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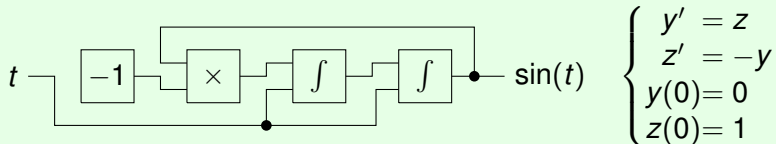


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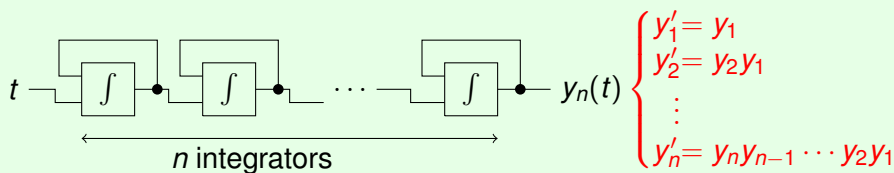


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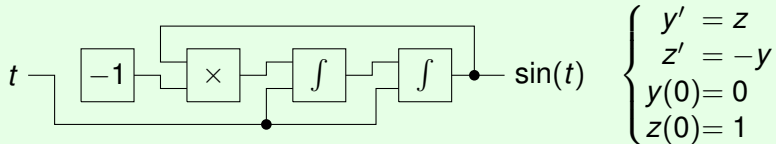


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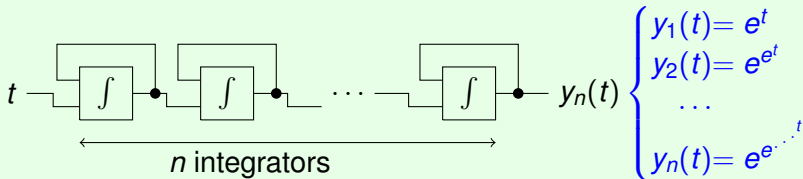


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Rational numbers, π , e , ...

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Example (Counter-Example)

$$r = \sum_{n=0}^{\infty} d_n 2^{-n}$$

where

$d_n = 1 \Leftrightarrow$ the n^{th} Turing Machine halts on input n

Computable function

Definition (Computable Function)

A function $f : \mathbb{R} \rightarrow \mathbb{R}$ is computable if there exist a Turing Machine M s.t. for any $x \in \mathbb{R}$ and oracle \mathcal{O} computing x , $M^{\mathcal{O}}$ computes $f(x)$.

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$$f(x) = \lceil x \rceil$$

Computable Analysis = GPAC ?

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Can we fix this ?

GPAC: back to the basics

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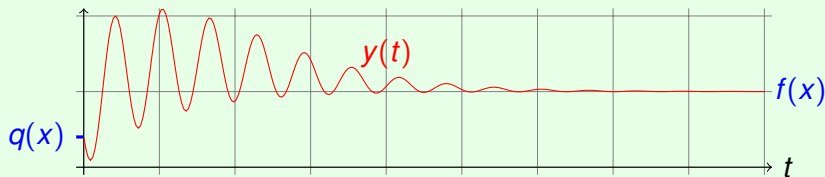
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Computable Analysis = GPAC ? (again)

Theorem 😊

The GPAC-computable functions are exactly the computable functions of the Computable Analysis.

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Theorem (😊)

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- Any solution to a PIVP is computable + convergence

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- Any solution to a PIVP is computable + convergence
- Simulate a Turing machine with a GPAC^a



^aDetails on blackboard

What about complexity ?

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Conjecture (😬)

Computable Analysis = General Purpose Analog Computer, *at the complexity level*

Time Scaling

System	#1	#2
ODE	$\begin{cases} y'(t) = p(y(t)) \\ y(1) = y_0 \end{cases}$	$\begin{cases} z'(t) = u(t)p(z(t)) \\ u'(t) = u(t) \\ z(t_0) = y_0 \\ u(1) = 1 \end{cases}$

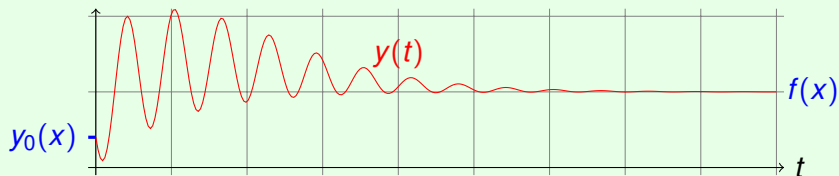
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Remark

Same curve, different speed: $u(t) = e^t$ and $z(t) = y(e^t)$

Example



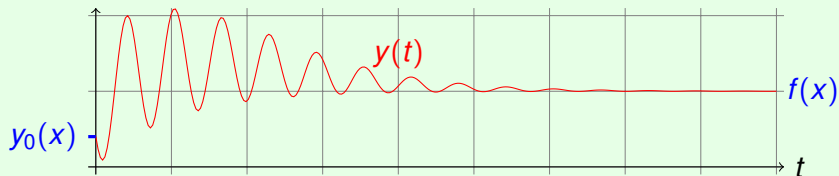
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Computed Function	$f(x) = \lim_{t \rightarrow \infty} y_1(t) = \lim_{t \rightarrow \infty} z_1(t)$	

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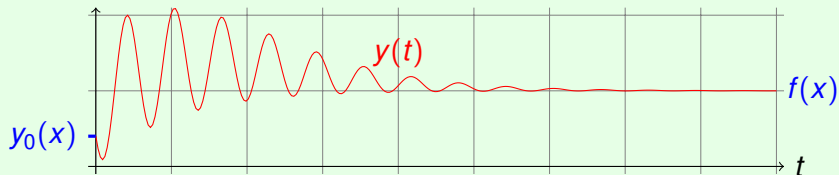
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Convergence	Eventually	Exponentially faster

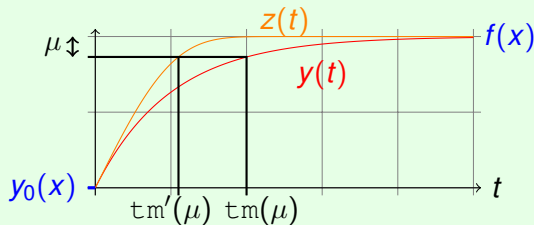
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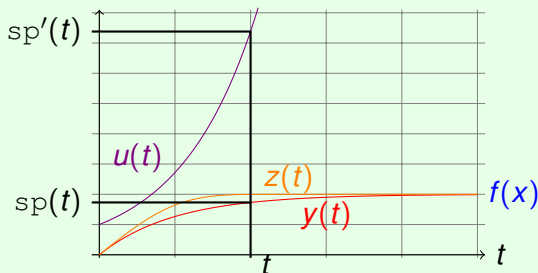


$$\|y_1(t_m(\mu)) - f(x)\| \leq \mu$$

Time Scaling

ODE	$y' = p(y)$	$\begin{cases} z' = up(z) \\ u' = u \end{cases}$
Computed Function	$f(x) = \lim_{t \rightarrow \infty} y_1(t) = \lim_{t \rightarrow \infty} z_1(t)$	
Time for precision μ	$\tau_m(\mu)$	$\tau_m'(\mu) = \log(\tau_m(\mu))$
Bounding box for ODE at time t	$sp(t)$	$sp'(t) = \max(sp(e^t), e^t)$

Example



$$sp(t) = \sup_{\xi \in [1, t]} \|y(\xi)\|$$

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Bounding box for ODE at precision μ	$\text{sp}(\text{tm}(\mu))$	$\max(\text{sp}(\text{tm}(\mu)), \text{tm}(\mu))$

Remark

- $\text{tm}(\mu)$ and $\text{sp}(t)$ depend on the convergence rate
- $\text{sp}(\text{tm}(\mu))$ seems not

Proper Measures

Proper measures of “complexity”:

- time scaling invariant
- property of the curve

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Possible choices:

- Bounding Box at precision $\mu \Rightarrow$ **Ok but geometric interpretation ?**
- Length of the curve until precision $\mu \Rightarrow$ **Much more intuitive**

Definition (Polytime GPAC-Computable Function)

f is **polytime** computable by a GPAC iff for all $x \in \mathbb{R}$ the solution $y = (y_1, \dots, y_d)$ of the ordinary differential equation (ODE):

$$\begin{cases} y' = p(y) \\ y(t_0) = q(x) \end{cases} \quad \text{where } p, q \text{ are vectors of polynomials}$$

satisfies $\|f(x) - y_1(\ell^{-1}(\text{len}(x, \mu)))\| \leq e^{-\mu}$ where

- len is a polynomial [polytime]
- $\ell(t)$ is the length of the curve y from t_0 to t .
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Remark

- implies $f(x) = \lim_{t \rightarrow \infty} y_1(t)$
- length of a curve: $\ell(t) = \int_{t_0}^t \|p(y(u))\| du$
- $y_1(\ell^{-1}(l)) =$ position after travelling a length l on the curve y

Computable Analysis = GPAC ?

Theorem (Almost ☹)

The polytime GPAC-computable functions are exactly the polytime computable functions of the Computable Analysis.

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Remark (Polytime computable in CA)

f polytime computable:

- polynomial modulus of continuity mc :
 $\|x - y\| \leq 2^{-mc(\mu)} \Rightarrow \|f(x) - f(y)\| \leq 2^{-\mu}$
- polynomial time computable over \mathbb{Q}

Conclusion

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- Equivalence with Computable Analysis for polynomial time

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Not mentioned in this talk:

- The GPAC as a language recogniser

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Not mentioned in this talk:

- The GPAC as a language recogniser
- Equivalence with P and NP

Future Work

- Notion of reduction ?

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- Space complexity ?

Questions ?

- Do you have any questions ?

GPAC as Language Recogniser

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 $f : \mathbb{N} \subseteq \mathbb{R} \rightarrow \{0, 1\} \subseteq \mathbb{R}$

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 $f : \mathbb{N} \subseteq \mathbb{R} \rightarrow \{0, 1\} \subseteq \mathbb{R}$
- **Yes but there is more !**

Definition (GPAC-Recognisable Language)

$\mathcal{L} \subseteq \mathbb{N}$ GPAC-recognisable if for any $x \in \mathbb{N}$, the solution y to

$$\begin{cases} y' = p(y) \\ y(t_0) = q(x) \end{cases} \quad \text{where } p, q \text{ are vectors of polynomials}$$

satisfies for $t \geq t_1(x)$:

- if $x \in \mathcal{L}$ then $y_1(t) \geq 1$ (accept)
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$\mathcal{L} \subseteq \mathbb{N}$ polytime GPAC-recognisable if for any $x \in \mathbb{N}$, the solution y to

$$\begin{cases} y' = p(y) \\ y(t_0) = q(x) \end{cases} \quad \text{where } p, q \text{ are vectors of polynomials}$$

satisfies for $t \geq t_1(x)$:

- if $x \in \mathcal{L}$ then $y_1(t) \geq 1$ (accept)
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The class of polytime GPAC-recognisable languages is exactly P .

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Remark (Why $\log(x)$?)

Classical complexity measure: length of word \approx log of value

Definition (Non-deterministic Polytime GPAC-Recognisable Language)

$\mathcal{L} \subseteq \mathbb{N}$ non-deterministic polytime GPAC-recognisable if for any $x \in \mathbb{N}$, the solution y to

$$\begin{cases} y' = p(y, u) \\ y(t_0) = q(x) \end{cases} \quad \text{where } p, q \text{ are vectors of polynomials}$$

satisfies for $t \geq t_1(x)$:

- if $x \in \mathcal{L}$ then $y_1(t) \geq 1$ for at least one digital controller u
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Remark (Digital Controller)

Digital Controller $\approx u : \mathbb{R} \rightarrow \{0, 1\}$

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Theorem

The class of non-deterministic polytime GPAC-recognisable languages is exactly *NP*.