

Simulating Induction-Recursion for Partial Algorithms in Coq

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`https://github.com/DmxLarchey/ite-normalisation`

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Standard Recursion in Coq

- Structural recursion, rec. calls on sub-terms

$$\text{fact } 0 = \text{S } 0 \quad \text{fact } (\text{S } n) = \text{S } n \times \text{fact } n$$

- Well-founded recursion for $R : X \rightarrow X \rightarrow \text{Prop}$ (module `Wf`)

Inductive `Acc R x : Prop :=`

| `Acc_intro` : $(\forall y, R y x \rightarrow \text{Acc } R y) \rightarrow \text{Acc } R x$.

`Fixpoint f x (Hx : Acc R x) {struct Hx} := ... f y Ty ...`

- Must define R before f , prove `Acc R x` and ensure $T_y <_{\text{struct}} H_x$
- Particular case, decreasing measure (using `lt_wf`):
 - $R x y$ is $m x < m y$ for some $m : X \rightarrow \text{nat}$
- This looks like strong constraints for general recursion...

Complicated recursive schemes

- No obvious structural recursion:

$$\text{min } f \ x = \text{if } f \ x = 0 \text{ then } x \text{ else min } f \ (1 + x)$$

- Nor obvious termination:

$$\text{iter}_0 \ f \ n = \text{if } n = 0 \text{ then } [] \text{ else } n :: \text{iter}_0 \ f \ (f \ n)$$

- Complicated termination proof ($\text{succs} : X \rightarrow \text{list } X$):

$$\text{dfs } v \ [] = v$$

$$\text{dfs } v \ (x :: l) = \text{dfs } v \ l \quad \text{if } x \in_1 l$$

$$\text{dfs } v \ (x :: l) = \text{dfs } (x :: v) \ (\text{succs } x \ ++ \ l) \quad \text{if } x \notin_1 l$$

More complicated recursive schemes

- Nesting/mutual recursion:

McCarthy F91 $f\ x = \text{if } x > 100 \text{ then } x - 10 \text{ else } f(f(x + 11))$

Knuth 1991 $f\ x = \text{if } x > a \text{ then } x - b \text{ else } f^c(x + d)$

- Nesting and hard termination proof: $\mathbb{U}\ (m \cdot n)\ (m' \cdot n')$ is

$$\begin{cases} \text{None} & \text{if } \mathbb{U}\ m\ m' = \text{None} \\ \text{None} & \text{if } \mathbb{U}\ m\ m' = \text{Some } \rho \text{ and } \mathbb{U}\ (\rho\ n)\ (\rho\ n') = \text{None} \\ \text{Some}(\sigma \circ \rho) & \text{if } \mathbb{U}\ m\ m' = \text{Some } \rho \text{ and } \mathbb{U}\ (\rho\ n)\ (\rho\ n') = \text{Some } \sigma \end{cases}$$

Beyond Coq structural recursion

- Induction-Recursion (IR) (Bove&Capretta 05)
 - general but IR absent from Coq
 - domain predicates are *informative* (extraction)
- Program Fixpoint or Equations (Sozeau 2010)
 - structural recursion or decreasing measure
 - for total functions
- Partial and Nested in HOL (Krauss 09)
 - versatile but non-constructive
 - needs Hilbert's ϵ description operator
- We want *accurate extraction* as well

Larry Paulson's normalization (1985)

let rec nm $e = \text{match } e \text{ with}$

| α $\rightarrow \alpha$

| $\omega(\alpha, y, z)$ $\rightarrow \omega(\alpha, \text{nm } y, \text{nm } z)$

| $\omega(\omega(a, b, c), y, z) \rightarrow \text{nm}(\omega(a, \text{nm}(\omega(b, y, z)), \text{nm}(\omega(c, y, z))))$

- α is atomic expression, $\omega b x y = \text{if } b \text{ then } x \text{ else } y$
- Pros:
 - recurring example (Giesl 97, B&C 05...)
 - has nested recursion, but compact and meaningful
- Cons:
 - Termination proof is somewhat easy (by a measure)
 - Could be done by Program Fixpoint

Inductive-Recursive schemes (Bove&Capretta 05)

Inductive $\Omega : \text{Set} := \alpha : \Omega \mid \omega : \Omega \rightarrow \Omega \rightarrow \Omega \rightarrow \Omega.$

Inductive $\mathbb{D} : \Omega \rightarrow \boxed{\text{Set}} :=$

| $\text{d_nm_0} \quad \quad \quad : \mathbb{D} \alpha$

| $\text{d_nm_1 } y \ z \quad \quad \quad : \mathbb{D} y \rightarrow \mathbb{D} z \rightarrow \mathbb{D}(\omega \ \alpha \ y \ z)$

| $\text{d_nm_2 } a \ b \ c \ y \ z \ D_b \ D_c \quad \quad \quad : \mathbb{D}(\omega \ a \ (\text{nm } (\omega \ b \ y \ z) \ D_b) \ (\text{nm } (\omega \ c \ y \ z) \ D_c))$
 $\rightarrow \mathbb{D}(\omega \ (\omega \ a \ b \ c) \ y \ z)$

with Fixpoint $\text{nm } e \ (D_e : \mathbb{D} \ e) \ \{\text{struct } D_e\} : \Omega := \text{match } D_e \ \text{with}$

| $\text{d_nm_0} \quad \quad \quad \mapsto \alpha$

| $\text{d_nm_1 } y \ z \ D_y \ D_z \quad \quad \quad \mapsto \omega \ \alpha \ (\text{nm } y \ D_y) \ (\text{nm } z \ D_z)$

| $\text{d_nm_2 } a \ b \ c \ y \ z \ D_b \ D_c \ D_a \ \mapsto \ \text{nm } (\omega \ a \ (\text{nm } (\omega \ b \ y \ z) \ D_b) \ (\text{nm } (\omega \ c \ y \ z) \ D_c)) \ D_a$

end.

- Coq does not have IR yet (but this might evolve shortly ?)
- The domain $\mathbb{D} : \Omega \rightarrow \text{Set}$ is *informative* (kept at extraction)

The graph method (Bove 09)

- a recursive scheme like `nm` induces a graph $\mathbb{G} : \Omega \rightarrow \Omega \rightarrow \text{Prop}$

$$\frac{}{\mathbb{G} \alpha \alpha} \quad \frac{\mathbb{G} y n_y \quad \mathbb{G} z n_z}{\mathbb{G} (\omega \alpha y z) (\omega \alpha n_y n_z)}$$

$$\frac{\mathbb{G} (\omega b y z) n_b \quad \mathbb{G} (\omega c y z) n_c \quad \mathbb{G} (\omega a n_b n_c) n_a}{\mathbb{G} (\omega (\omega a b c) y z) n_a}$$

- She defines the *informative* domain predicate $\mathbb{D} e := \{n \mid \mathbb{G} e n\}$
- $\mathbb{D} : \Omega \rightarrow \boxed{\text{Set}}$ is then used for `nm` e ($D_e : \mathbb{D} e$) $:= \pi_1(D_e)$
 - and `nm_spec` $e D_e : \mathbb{G} e (\text{nm } e D_e)$ as $\pi_2(D_e)$
- Problem: computational content of `nm` equals that of D_e
 - extracted code for `nm` e depends on the proof term $D_e : \mathbb{D} e$
 - establishing $\mathbb{D} e$ must follow strict rules to get the good code

We obtain this simulated IR scheme

Inductive $\mathbb{D} : \Omega \rightarrow \boxed{\text{Prop}} :=$

d_nm_0		: $\mathbb{D} \alpha$
d_nm_1	$y z$: $\mathbb{D} y \rightarrow \mathbb{D} z \rightarrow \mathbb{D}(\omega \alpha y z)$
d_nm_2	$a b c y z D_b D_c$: $\mathbb{D}(\omega a (\text{nm } (\omega b y z) D_b) (\text{nm } (\omega c y z) D_c))$ $\rightarrow \mathbb{D}(\omega (\omega a b c) y z)$

with Fixpoint $\text{nm } e (D_e : \mathbb{D} e) : \Omega := \text{match } D_e \text{ with}$

d_nm_0		$\mapsto \alpha$
d_nm_1	$y z D_y D_z$	$\mapsto \omega \alpha (\text{nm } y D_y) (\text{nm } z D_z)$
d_nm_2	$a b c y z D_b D_c D_a$	$\mapsto \text{nm } (\omega a (\text{nm } (\omega b y z) D_b) (\text{nm } (\omega c y z) D_c)) D_a$

end.

- The domain $\mathbb{D} : \Omega \rightarrow \text{Prop}$ is *non-informative* (good extraction)
- $\text{nm} : \forall e, \mathbb{D} e \rightarrow \Omega$ is *proof-irrelevant*, i.e. $\text{nm } x D_1 = \text{nm } x D_2$
- We get constructors, a dep. elim. scheme and fixpoint eqs

The graph and the domain revisited

- Recall `nm` induces a graph $\mathbb{G} : \Omega \rightarrow \Omega \rightarrow \mathbf{Prop}$

$$\frac{}{\mathbb{G} \alpha \alpha} \quad \dots \quad \frac{\mathbb{G} (\omega b y z) n_b \quad \mathbb{G} (\omega c y z) n_c \quad \mathbb{G} (\omega a n_b n_c) n_a}{\mathbb{G} (\omega (\omega a b c) y z) n_a}$$

- \mathbb{G} is functional: `g_nm_fun` : $\forall e n_1 n_2, \mathbb{G} e n_1 \rightarrow \mathbb{G} e n_2 \rightarrow n_1 = n_2$
- we define the *non-informative* domain $\mathbb{D} e := \exists n, \mathbb{G} e n$
- inductive structure on $\mathbb{D} : \Omega \rightarrow \mathbf{Prop}$ provided by the `nm` scheme
 - for $e \in \mathbb{D}$, $m(e)$ = number of rec. calls to compute `nm e`
 - well-founded relation of \mathbb{D} : $R x y$ iff $m(x) < m(y)$
 - Problem: defining $m : \mathbb{D} \rightarrow \mathbf{nat}$ as hard as defining `nm` : $\mathbb{D} \rightarrow \Omega$

The inductive structure of $\mathbb{D} : \Omega \rightarrow \text{Prop}$ (i)

- Non-informative capture by accessibility predicates (**Wf**)
- The relation $<_{\mathbb{R}} : \Omega \rightarrow \Omega \rightarrow \text{Prop}$ relates calls to sub-calls

$$\begin{array}{c}
 \frac{}{y <_{\mathbb{R}} \omega \alpha y z} \quad \frac{}{z <_{\mathbb{R}} \omega \alpha y z} \quad \frac{}{\omega b y z <_{\mathbb{R}} \omega (\omega a b c) y z} \\
 \frac{\mathbb{G} (\omega b y z) n_b \quad \mathbb{G} (\omega c y z) n_c}{\omega a n_b n_c <_{\mathbb{R}} \omega (\omega a b c) y z} \quad \frac{}{\omega c y z <_{\mathbb{R}} \omega (\omega a b c) y z}
 \end{array}$$

- $\mathbb{D} = \text{fun } e \mapsto \exists n, \mathbb{G} e n$ is well-founded: $\forall e, \mathbb{D} e \rightarrow \text{Acc } <_{\mathbb{R}} e$
- We define `nm_rec` by structural induction on A_e :

Fixpoint `nm_rec` $e (A_e : \text{Acc } <_{\mathbb{R}} e) \{\text{struct } A_e\} : \{n \mid \mathbb{G} e n\} := \dots$

The inductive structure of $\mathbb{D} : \Omega \rightarrow \text{Prop}$ (ii)

- Capture \mathbb{D} as bar inductive predicate

$$\frac{}{\mathbb{G} \alpha \alpha} \quad \frac{\mathbb{G} y n_y \quad \mathbb{G} z n_z}{\mathbb{G} (\omega \alpha y z) (\omega \alpha n_y n_z)}$$

$$\frac{\mathbb{G} (\omega b y z) n_b \quad \mathbb{G} (\omega c y z) n_c \quad \mathbb{G} (\omega a n_b n_c) n_a}{\mathbb{G} (\omega (\omega a b c) y z) n_a}$$

- $\mathbb{D} : \Omega \rightarrow \text{Prop}$ inductively defined:

$$\frac{\mathbb{D} y \quad \mathbb{D} z \quad \forall n_b n_c, \mathbb{G} (\omega b y z) n_b \rightarrow \mathbb{G} (\omega c y z) n_c \rightarrow \mathbb{D} (\omega a n_b n_c)}{\mathbb{D} \alpha \quad \mathbb{D} (\omega \alpha y z) \quad \mathbb{D} (\omega (\omega a b c) y z)}$$

- We define `nm_rec` by structural induction on D_e :

Fixpoint `nm_rec e (D_e : \mathbb{D} e) {struct D_e} : {n | $\mathbb{G} e n$ } := ...`

The definition of `nm_rec` : $\forall e, \mathbb{D} e \rightarrow \{n \mid \mathbb{G} e n\}$

Let `nm_rec` : $\forall e, \mathbb{D} e \rightarrow \{n \mid \mathbb{G} e n\}$.

`refine(fix loop e De {struct De} :=`

`match e as e' return $\mathbb{D} e' \rightarrow \{n \mid \mathbb{G} e' n\}$ with`

`| α \mapsto fun D \mapsto exist - α $\mathbb{G}_0^?$`

`| $\omega \alpha y z$ \mapsto fun D \mapsto let $(n_y, H_y) :=$ loop y $\mathbb{T}_y^?$ in
let $(n_z, H_z) :=$ loop z $\mathbb{T}_z^?$
in exist - $(\omega \alpha n_y n_z)$ $\mathbb{G}_1^?$`

`| $\omega (\omega a b c) y z$ \mapsto fun D \mapsto let $(n_b, H_b) :=$ loop $(\omega b y z)$ $\mathbb{T}_b^?$ in
let $(n_c, H_c) :=$ loop $(\omega c y z)$ $\mathbb{T}_c^?$ in
let $(n_a, H_a) :=$ loop $(\omega a n_b n_c)$ $\mathbb{T}_a^?$
in exist - n_a $\mathbb{G}_2^?$`

`end De); simpl in *.`

Proof. of certificates $\mathbb{T}_y^?, \mathbb{T}_z^?, \mathbb{T}_b^?, \mathbb{T}_c^?, \mathbb{T}_a^?$ and post-conditions $\mathbb{G}_0^?, \mathbb{G}_1^?, \mathbb{G}_2^?$ Qed.

Proof obligations (non-informative part)

- Post-conditions by the constructors of \mathbb{G}

$$\mathbb{G}_0^? // \dots \vdash \mathbb{G} \alpha \alpha$$

$$\mathbb{G}_1^? // \dots, H_y : \mathbb{G} y n_y, H_z : \mathbb{G} z n_z \vdash \mathbb{G} (\omega \alpha y z) (\omega \alpha n_y n_z)$$

$$\mathbb{G}_2^? // \dots, H_b : \mathbb{G} (\omega b y z) n_b, H_c : \mathbb{G} (\omega c y z) n_c, \dots$$

$$\dots H_a : \mathbb{G} (\omega a n_b n_c) n_a \vdash \mathbb{G} (\omega (\omega a b c) y z) n_a$$

- Termination certificates by **inversion** lemmas

$$\mathbb{T}_y^? // \dots, D : \mathbb{D} (\omega \alpha y z) \vdash \mathbb{D} y$$

$$\mathbb{T}_b^? // \dots, D : \mathbb{D} (\omega (\omega a b c) y z) \vdash \mathbb{D} (\omega b y z)$$

$$\mathbb{T}_a^? // \dots, D : \mathbb{D} (\omega (\omega a b c) y z), H_b : \mathbb{G} (\omega b y z) n_b, \dots$$

$$\dots H_c : \mathbb{G} (\omega c y z) n_c \vdash \mathbb{D} (\omega a n_b n_c)$$

- beware of structural decrease in termination certificates

Reification of the graph predicate $\mathbb{G} : \Omega \rightarrow \Omega \rightarrow \text{Prop}$

- with `nm_rec` we obtain a *reifier* of the graph \mathbb{G}

$$(\exists n, \mathbb{G} e n) \rightarrow \left(\frac{\text{Acc } <_{\mathbb{R}} e}{\mathbb{D} e} \right) \rightarrow \{n \mid \mathbb{G} e n\}$$

- hence we can show: $\exists n, \mathbb{G} e n$ iff $\text{Acc } <_{\mathbb{R}} e$ iff $\mathbb{D} e$
- we define `nm e De` := $\pi_1(\text{nm_rec } e D_e)$
- we get `nm_spec e De` : $\mathbb{G} e (\text{nm } e D_e)$ as $\pi_2(\text{nm_rec } e D_e)$
 - with simulated constructors for \mathbb{D}
 - with dependent elimination scheme for \mathbb{D}
 - proof irrelevance for `nm`, fixpoints equations for `nm`

Extraction independent of the domain

- In $\text{nm } e (D_e : \mathbb{D} e) : \Omega$, extraction erases the term $D_e : \mathbb{D} e : \text{Prop}$

- Hence `Extraction nm` gives the intended term:

`let rec nm e = match e with`

`| α → α`

`| $\omega(x, y, z)$ → match x with`

`| α → $\omega(\alpha, \text{nm } y, \text{nm } z)$`

`| $\omega(a, b, c)$ → nm($\omega(a, \text{nm}(\omega(b, y, z)), \text{nm}(\omega(c, y, z)))$)`

- the proof of $D_e : \mathbb{D} e$ can be provided:
 - after both $\mathbb{D} : \Omega \rightarrow \text{Prop}$ and $\text{nm} : \forall e, \mathbb{D} e \rightarrow \Omega$ are defined
 - by any means necessary w/o consequences on extracted code

Dependent elimination scheme for $\mathbb{D} : \Omega \rightarrow \text{Prop}$

Fact `d_nm_0` : $\mathbb{D} \alpha$.

Fact `d_nm_1` : $\forall y z, \mathbb{D} y \rightarrow \mathbb{D} z \rightarrow \mathbb{D} (\omega \alpha y z)$.

Fact `d_nm_2` : $\forall a b c y z (D_b : \mathbb{D} (\omega b y z)) (D_c : \mathbb{D} (\omega c y z)),$
 $\mathbb{D} (\omega a (\text{nm} - D_b) (\text{nm} - D_c)) \rightarrow \mathbb{D} (\omega (\omega a b c) y z)$.

Variables $(P : \forall e, \mathbb{D} e \rightarrow \text{Type})$

$(HP_i : \forall e D_1 D_2, P e D_1 \rightarrow P e D_2)$

$(HP_0 : P \alpha \text{d_nm_0})$

$(HP_1 : \forall y z D_y (- : P - D_y) D_y (- : P - D_z), P - (\text{d_nm_1} y z D_y D_z))$

$(HP_2 : \forall a b c y z D_b (- : P - D_b) D_c (- : P - D_c) \dots$

$\dots D_a (- : P - D_a), P - (\text{d_nm_2} a b c y z D_b D_c D_a))$

Theorem `d_nm_rect` : $\forall e, \mathbb{D} e \rightarrow P e D_e$.

- Hypothesis HP_i restricts to proof-irrelevant properties

Proof-irrelevance and fixpoint equations

Fact `nm_pirr` : $\forall e D_1 D_2, \text{nm } e D_1 = \text{nm } e D_2.$

Fact `nm_fix_0` : $\text{nm } \alpha \text{ d_nm_0} = \alpha.$

Fact `nm_fix_1` : $\forall y z D_y D_z,$

$$\begin{aligned} & \text{nm } (\omega \alpha y z) (\text{d_nm_1 } y z D_y D_z) \\ & = \omega \alpha (\text{nm } y D_y) (\text{nm } z D_z). \end{aligned}$$

Fact `nm_fix_2` : $\forall a b c y z D_b D_c D_a,$

$$\begin{aligned} & \text{nm } (\omega (\omega a b c) y z) (\text{d_nm_2 } a b c y z D_b D_c D_a) \\ & = \text{nm } (\omega a (\text{nm } (\omega b y z) D_b) (\text{nm } (\omega c y z) D_c)) D_a. \end{aligned}$$

- With `nm_pirr`, `d_nm_rect` is sufficient for partial correction:
 - `nm_normal` : $\forall e (D_e : \mathbb{D} e), \text{normal } (\text{nm } e D_e)$
 - `nm_equiv` : $\forall e (D_e : \mathbb{D} e), e \simeq_{\Omega} \text{nm } e D_e$
 - `nm_dec` : $\forall e (D_e : \mathbb{D} e), |\text{nm } e D_e| \leq |e|$ ($|e|$ defined next slide)

Totality of \mathbb{D} / Termination of nm

- As in Giesl 97, we define $|\cdot| : \Omega \rightarrow \text{nat}$ as:
 - $|\alpha| = 1$ and $|\omega x y z| = |x| \times (1 + |y| + |z|)$
- We show `d_nm_total` : $\forall e, \mathbb{D} e$ by induction on $|e|$
 - we use `nm_dec` : $\forall e (D_e : \mathbb{D} e), |\text{nm } e D_e| \leq |e|$
 - $|\omega x y z| \leq |\omega x' y' z'|$ when $|x| \leq |x'|, |y| \leq |y'|, |z| \leq |z'|$
 - and $|\omega u y z| < |\omega v y z|$ when $|u| < |v|$
 - and $|y| < |\omega x y z|$ and $|z| < |\omega x y z|$
 - and $|\omega a (\omega b y z) (\omega c y z)| < |\omega (\omega a b c) y z|$
- Partial correction / termination independently of definition

$$\text{paulson_nm} : \forall e : \Omega, \{n_e : \Omega \mid e \simeq_{\Omega} n_e \wedge \text{normal } e\}$$

Other Example, Knuth F91 (1991) (i)

```
let rec f x = if x ≤ a then fc(x + d) else x - b
    and fn x = if n = 0 then x else fn-1(f x)
```

```
Inductive df : nat → Prop :=
```

```
| df_0 x : a < x → df x
```

```
| df_1 x : x ≤ a → df* c (x + d)
```

```
with df* : nat → nat → Prop :=
```

```
| df_0* x : df* 0 x
```

```
| df_1* n x (Dx : df x) : df* n (f x Dx) → df* (S n) x
```

```
with Fixpoint f x (D : df x) : nat := match D with
```

```
| df_0 x Hx ↦ x - b
```

```
| df_1 x Hx Dc ↦ f* c (x + d) Dc end
```

```
with Fixpoint f* n x (D : df* n x) : nat := match D with
```

```
| df_0* x ↦ x
```

```
| df_1* n x Dx Dn ↦ f* n (f x Dx) Dn end.
```

Other Example, Knuth F91 (1991) (ii)

- We ignore the case $c = 0$ (there is no recursion)
- For $d \leq b(c - 1)$, f is partial:
 - For any $\mathbb{G} : \text{nat} \rightarrow \text{nat} \rightarrow \text{Prop}$ closed under

$$\frac{a < x}{\mathbb{G} \ x \ (x - b)} \qquad \frac{x \leq a \quad \mathbb{G}^c \ (x + d) \ y}{\mathbb{G} \ x \ y}$$

- Graph induction: $\text{Thm } f_graph_ind : \forall x \ D_x, \mathbb{G} \ x \ (f \ x \ D_x)$
- use it for $\mathbb{G} \ x \ y$ iff $a < x \wedge y = x - b$
- much simpler than Knuth proof, stronger characterization
- For $b(c - 1) < d$, f is total and solution of:
 - $f \ x = \text{if } x \leq a \text{ then } f \ (x + d - b(c - 1)) \ \text{else } x - b$

Other Examples

- DFS, unification: difficult termination argument
- Huet&Hullot list reversal: mutual induction
- Matrix diagonal (dependently typed)
- minimization and μ -recursive functions (a “compact” interpreter)

Perspectives

- complete the bestiary
- automation, what is the best user interface (IR or graph)?

Depth First Search (nice but not nested)

Inductive `ddfs` : `list X` \rightarrow `list X` \rightarrow `Prop` :=

| `ddfs_0 v` : `ddfs v nil`

| `ddfs_1 v x l` : $x \in_1 v \rightarrow \text{ddfs } v \ l \rightarrow \text{ddfs } v \ (x :: l)$

| `ddfs_2 v x l` : $x \notin_1 v \rightarrow \text{ddfs } (x :: v) \ (\text{succs } x \ ++ \ l) \rightarrow \text{ddfs } v \ (x :: l)$

with Fixpoint `dfs v l (D : ddfs v l) : list X` := `match D with`

| `ddfs_0 v` $\mapsto v$

| `ddfs_1 v x l _ D` $\mapsto \text{dfs } v \ l \ D$

| `ddfs_2 v x l _ D` $\mapsto \text{dfs } (x :: v) \ (\text{succs } x \ ++ \ l) \ D$

end.

- for $X : \text{Type}$ and $\text{succs} : X \rightarrow \text{list } X$
- $\mathbb{I} \ v \ l \ m := v \ ++ \ l \subseteq_1 \ m \wedge \forall x, x \in_1 \ m \rightarrow (x \in_1 \ v \vee \text{succs } x \subseteq_1 \ m)$
- $\text{dfs_correct } v \ l \ D : \mathbb{I} \ v \ l \ (\text{dfs } v \ l \ D) \wedge \forall m, \mathbb{I} \ v \ l \ m \rightarrow \text{dfs } D \subseteq_1 \ m$
- $\text{dfs_domain } v \ l : \text{ddfs } v \ l \iff \exists m, \mathbb{I} \ v \ l \ m$

μ -recursive algos extraction (improves ITP'17)

Thm `ra_compute` $k (a : \text{recalg } k) \vec{v} : (\exists x, \llbracket a \rrbracket \vec{v} x) \rightarrow \{x \mid \llbracket a \rrbracket \vec{v} x\}$

```
let min_compute f =
```

```
  let rec loop n = match f n with 0 → n | S _ → loop (S n) in loop 0
```

```
(** val ra_compute : recalg → nat vec → nat **)
```

```
let rec ra_compute a  $\vec{v}$  =
```

```
  match a with
```

```
    | Ra_cst n      → n
```

```
    | Ra_zero      → 0
```

```
    | Ra_succ      → S  $\vec{v}_0$ 
```

```
    | Ra_proj p    →  $\vec{v}_p$ 
```

```
    | Ra_comp (f,  $\vec{g}$ ) → ra_compute f (vec_compute (fun h → ra_compute h  $\vec{v}$ )  $\vec{g}$ )
```

```
    | Ra_prim (f, g) → prim_compute (fun  $\vec{w}$  → ra_compute f  $\vec{w}$ )
```

```
      (fun x y  $\vec{w}$  → ra_compute g (x#y# $\vec{w}$ )) (vtail  $\vec{v}$ )  $\vec{v}_0$ 
```

```
    | Ra_min f      → min_compute (fun x → ra_compute f (x# $\vec{v}$ ))
```